

A Review of an Old Dilemma: Demosaicking First, or Denoising First?

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IMU and Centre Borelli

NTIRE2020 Workshop – 15 June, 2020

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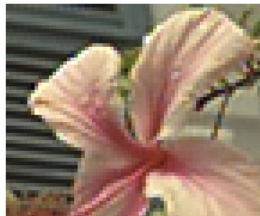
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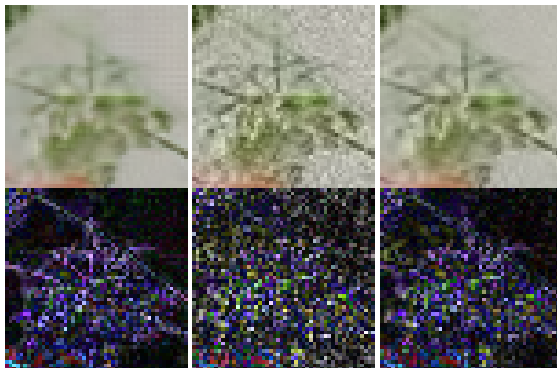
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**Demosaic
& Denoise**



Denoise→Demosaic vs Demosaic→Denoise



(a) $DN\&DM$ /26.92dB

(b) $DM\&DN$ /25.38dB

(c) $DM\&1.5DN$ /26.95dB

$DN\&DM$ Pros: iid AWG Cons: over-smooth, checkerboard effects

$DM\&DN$ Pros: more details, no checkerboard effects Cons: chromatic and spatial correlations noise

Analyze the demosaicking noise

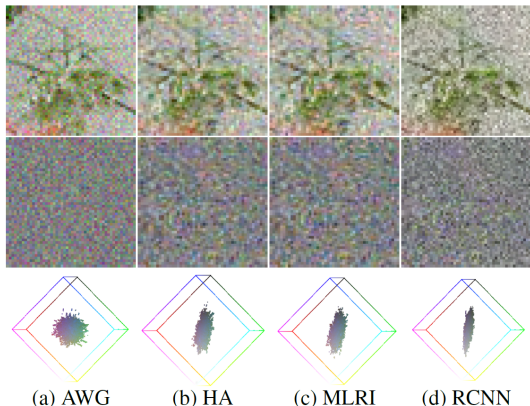


Figure: AWG noise image and demosaicking noise with standard deviation $\sigma = 20$ for respectively HA[1], MLRI[2], RCNN[3]. Last row: the color spaces (in standard (R,G,B) Cartesian coordinates) of each noise, presented in their projection with maximal area.

Variance and covariance of (R, G, B) and (Y, C_1, C_2)

	(i,j)	$(i,j+1)$	$(i,j+2)$	$(i+1,j)$	$(i+1,j+1)$	$(i+1,j+2)$	$(i+2,j)$	$(i+2,j+1)$	$(i+2,j+2)$
R	400.6	0.6	0.4	0.7	0.1	0.7	0.3	0.2	0.8
G	401.7	0.5	1.1	0.1	0.3	0.9	1.0	0.6	0.4
B	400.2	1.2	0.1	0.5	0.6	0.0	1.9	0.3	1.9
Y	399.6	1.1	0.1	0.3	0.1	0.9	0.2	0.5	1.2
C_1	401.5	0.1	0.8	0.6	0.3	0.3	0.9	0.5	1.3
C_2	401.4	0.2	1.8	0.9	0.2	1.0	0.6	0.2	0.2

(a) AWG noise

	(i,j)	$(i,j+1)$	$(i,j+2)$	$(i+1,j)$	$(i+1,j+1)$	$(i+1,j+2)$	$(i+2,j)$	$(i+2,j+1)$	$(i+2,j+2)$
R	359.9	47.8	5.0	51.9	21.8	17.8	5.1	19.4	9.2
G	354.8	32.6	4.4	36.3	5.8	8.4	6.4	8.8	0.6
B	356.0	49.6	6.3	53.7	23.6	18.8	7.3	19.4	9.2
Y	972.3	69.0	20.8	76.4	3.6	18.6	28.9	17.3	2.2
C_1	55.1	33.8	15.3	36.0	26.1	14.6	19.0	16.6	11.8
C_2	43.3	27.3	12.3	29.4	21.5	11.7	16.0	13.7	9.4

(c) RCNN

Summary of experiments (simulated images)

Table: Comparison of the results (CPSNR in dB) changing the order of denoising and demosaicking for the **Kodak** image set.

σ	<i>DN&DM</i>	<i>DM&1.5DN</i>
	BM3D+RCNN	RCNN+CBM3D
1	40.55	40.98
5	34.89	36.55
10	30.93	33.36
20	27.70	29.98
40	24.78	26.71
60	22.55	24.42
Av	28.35	30.19

Summary of experiments (real images)

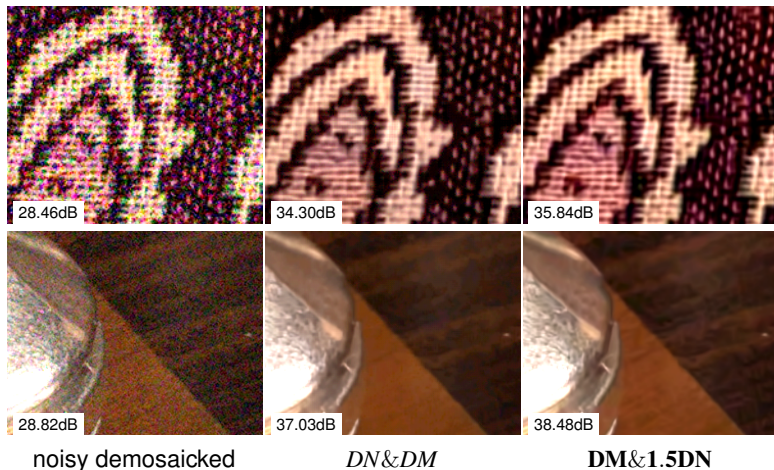


Figure: Details of a real images (enhanced contrast) from the SIDD [8] dataset. From left to right: noisy input (demosaicked), BM3D+RCNN , and RCNN+CBM3D.



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